

**IN THE CLAIMS:**

The text of all pending claims, (including withdrawn claims) is set forth below. Cancelled and not entered claims are indicated with claim number and status only. The claims as listed below show added text with underlining and deleted text with ~~strikethrough~~. The status of each claim is indicated with one of (original), (currently amended), (cancelled), (withdrawn), (new), (previously presented), or (not entered).

1. (currently amended) A robot including a moving mechanism for causing the robot to move freely, comprising:

a communication section which wirelessly connects to a communication line;

a detection section which detects a plurality of user requests, provided by a user, via an input device upon occurrence of an event;

a storing section which stores telephone numbers, wherein each of the telephone numbers is associated with a respective emergency reporting item comprising a priority sequence, a designation mode of one of the user requests and an associated message; and

a telephone control section which causes the communication section to dial one of the telephone numbers stored in the storing section in response to the detection section detecting the respective designation mode of one of the user requests, and then delivers the associated message stored in the storing section as a voice message to a receiver when the receiver responds.

2. (canceled)

3. (previously presented) A robot according to claim 1, further comprising a microphone and a speaker, and wherein the telephone control section causes, after delivering the associated message to the receiver, the communication section to be in a state of communication using the microphone and the speaker.

4. (original) A robot according to claim 1, further comprising an e-mail transmission function,  
wherein the storing section further stores an e-mail address and a message associated with the e-mail,  
wherein the detection section detects a plurality of modes of requests, and  
wherein the telephone control section transmits, according to a mode of request detected by the detection section, the message associated with the e-mail address stored in the storing section.

5. (original) A robot according to claim 4, wherein the telephone control section dials a telephone number according to a mode of request detected by the detection section when the detected mode of request is a telephone mode, and then the telephone control section transmits the message to the e-mail address stored in the storing section when a receiver does not respond.

6. (original) A robot according to claim 1, further comprising:  
a microphone;  
a voice recognition section which recognizes that the robot is called based on a voice received by the microphone; and  
a movement control section which controls, when the voice recognition section recognizes that the robot is called, the moving mechanism so as to move the robot closer to a speaker who is calling the robot.

7. (previously presented) A robot according to claim 1, wherein said telephone control section delivers the associated message based on one of the priority sequences associated with the designation mode of one of the user requests.

8. (previously presented) A robot according to claim 1, wherein the designation mode of a respective one of the user requests is determined by the user pressing a request button in a respective one of a plurality of coded sequences.

9. (previously presented) The robot according to claim 1, wherein the delivered associated message is  
a voice message delivered to a receiver when the receiver responds.

10. (currently amended) A method of having a free moving robot detect a user emergency request and report an emergency in response, the method comprising:

detecting from among any of a plurality of emergency requests stored in a memory in a priority sequence with an associated designation mode and telephone number, an emergency request, provided by a user, via an input device upon occurrence of an event; and

dialing a telephone number associated with the emergency request in response to the respective designation mode of the detected emergency request, the robot communicating wirelessly.